UESTC Referencing Style

How to use on Mendeley Tutorial

# My Heading

This is a tutorial on how to add the UESTC Referencing style to your Mendeley Reference Manager[1][2].

## Lorem Ipsum

Lorem ipsum dolor sit amet, consectetur adipiscing elit, sed do eiusmod tempor incididunt ut labore et dolore magna aliqua. Excepteur sint occaecat cupidatat non proident, sunt in culpa qui officia deserunt mollit anim id est laborum[3].

## Random Heading

Sed ut perspiciatis unde omnis iste natus error sit voluptatem accusantium doloremque laudantium, totam rem aperiam, eaque ipsa quae ab illo inventore veritatis et quasi architecto beatae vitae dicta sunt explicabo[4][5]. Nemo enim ipsam voluptatem ratione voluptatem sequi im nesciunt[6]–[8].

## References

[1] Differential Drive: Mechanism & Explained | StudySmarter [OL].

[2] A Short History of Robot Vacuums and Docks - HubPages [OL].

[3] Moshe P. Mann and Zvi Shiller. Dynamic Stability of a Rocker Bogie Vehicle: Longitudinal Motion [M]. 2006.

[4] X. Wang, X. Ma, and Z. Li. Research on SLAM and Path Planning Method of Inspection Robot in Complex Scenarios [X]. 11-Apr-2023.

[5] X. Xu, L. Zhang, J. Yang, et al. A Review of Multi-Sensor Fusion SLAM Systems Based on 3D LIDAR [X]. Remote Sensing, 01-Jun-2022, 14(12).

[6] R. Yadav and R. Kala. Fusion of visual odometry and place recognition for SLAM in extreme conditions [J]. Applied Intelligence, 2022, 52(10): 11928–11947.

[7] A. F. Panaite and L. Bogdanffy. Reimagining vision with infinity mirrors [J].

[8] G. Song, H. Wang, J. Zhang, et al. Automatic docking system for recharging home surveillance robots [J]. IEEE Transactions on Consumer Electronics, 2011, 57(2): 428–435.

Note the [X] on the fourth and fifth references. This is because the actually type has not been specified. Specify the type in your reference manager for the best referencing results.